Theorem 17: Equal corresponding angles mean that lines are parallel.

<u>Corollary 1</u>: Equal alternate interior angles mean that lines are parallel.

<u>Corollary 2</u>: Supplementary interior angles on the same side of a transversal

mean that lines are parallel.

Corollary 3: In a plane, two lines perpendicular to a third line are parallel.

<u>The Parallel Postulate</u> – Through a point not on a line, there is exactly one line parallel to the given line.

Theorem 18: In a plane, two lines parallel to a third line are parallel to each other.

<u>Theorem 19</u>: Parallel lines form equal corresponding angles.

Corollary 1: Parallel lines form equal alternate interior angles.

Corollary 2: Parallel lines form supplementary interior angles on the same side of a transversal.

Corollary 3: In a plane, a line perpendicular to one of two parallel lines is also perpendicular to the other.

<u>Theorem 20</u>: The Triangle Sum Theorem – The sum of the angles of a triangle is 180°.

Corollary 1: If two angles of one triangle are equal to two angles of another

triangle, the third angles are equal.

Corollary 2: The acute angles of a right triangle are complementary.

Corollary 3: Each angle of an equilateral triangle is 60°.

<u>Theorem 21</u>: An exterior angle of a triangle is equal to the sum of the remote interior angles.

<u>Theorem 22</u>: <u>The AAS Theorem</u> – If two angles and the side opposite one of them in one triangle are equal to the corresponding parts of another triangle, the triangles are congruent.

<u>Theorem 23</u>: <u>The HL Theorem</u> – If the hypotenuse and a leg of one right triangle are equal to the corresponding parts of another right triangle, the triangles are congruent.

SSS, SAS, AAS, ASA, HL

Def: A <u>diagonal</u> of a polygon is a line segment that connects any two nonconsecutive vertices.

Theorem 24: The sum of the angles of a quadrilateral is 360°.

Def: A <u>rectangle</u> is a quadrilateral each of whose angles is a right angle.

Corollary to Theorem 24:A quadrilateral is equiangular iff it is a rectangle.

In general, if a polygon has n sides, in terms of n,

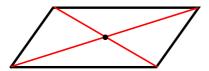
- n-3 diagonals can be drawn from one vertex
- these diagonals form n-2 triangles
- the sum of the angles of an n-gon is (n-2)*180°
- If the n-gon is equiangular, each angle measures (n-2)*180°/n

Def: A <u>parallelogram</u> is a quadrilateral whose opposite sides are parallel.

A figure has point symmetry if it looks exactly the same when it is rotated about a point.

Def: Two points are symmetric with respect to a point iff it is the midpoint of the line segment joining them.

Parallelograms have point symmetry about the point in which their diagonals intersect.



Theorem 25: The opposite sides and angles of a parallelogram are equal.

Theorem 26: The diagonals of a parallelogram bisect each other.

Theorem 27: A quadrilateral is a parallelogram, if its opposite sides are equal.

Theorem 28: A quadrilateral is a parallelogram if its opposite angles are equal.

<u>Theorem 29</u>: A quadrilateral is a parallelogram if two opposite sides are both parallel and equal.

Theorem 30: A quadrilateral is a parallelogram if its diagonals bisect each other.

7.4 – Rectangles, Rhombuses, and Squares

Def: A square is a quadrilateral all of whose sides and angles are equal.

Every square is a rhombus.

Def: A rhombus is a quadrilateral all of whose sides are equal.

Theorem 31: All rectangles are parallelograms.

Theorem 32: All rhombuses are parallelograms.

Theorem 33: The diagonals of a rectangle are equal.

Theorem 34: The diagonals of a rhombus are perpendicular.

Def: A trapezoid is a quadrilateral that has exactly one pair of parallel sides.

The parallel sides are called the <u>bases</u> of the trapezoid, and the non-parallel sides are called its <u>legs</u>. The pairs of angles that include each base are called <u>base angles</u>.

Def: An isosceles trapezoid is a trapezoid whose legs are equal.

<u>Theorem 35</u>: The base angles of an isosceles trapezoid are equal.

Theorem 36: The diagonals of an isosceles trapezoid are equal.

If a quadrilateral is a trapezoid, then its diagonals cannot bisect each other.

Def: A <u>midsegment</u> of a triangle is a line segment that connects the midpoints of two of its sides.

<u>Theorem 37</u>: <u>The Midsegment Theorem</u> – A midsegment of a triangle is parallel to the third side and half as long.

Regular dodecagon

1. How many sides does a dodecagon have?



12 Sides
A regular polygon is one that is equilateral and equiangular.

2. How many regular quadrilaterals do there seem to be in the figure?



3. What is a regular quadrilateral called?



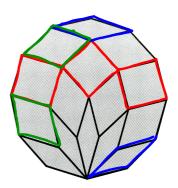
4. How many rectangles do there seem to be in the figure?



5. How many rhombuses are in the figure?



6. How many different shapes of rhombuses does the figure seem to contain?



8.1 - Transformations

Def: A transformation is a one-to-one correspondence between two sets of points.

A translation slides an object a certain distance without turning it.

A reflection flips an object over a mirror line.

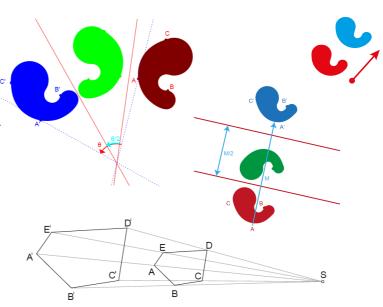
A rotation turns an object a certain number of degrees about a fixed point.

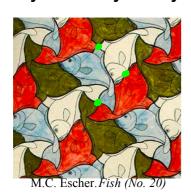
A dilation enlarges or reduces the size of an object.

Def: an isometry is a transformation that preserves distance and angle measure.

Translations, reflections, and rotations

are all examples of isometries, but dilations are not.





What type of translation seems to relate

1. Two fish of the same color?

translation

2. A pair of red and white fish?

rotation

3. A pair of blue and white fish?

rotation

Are there any pairs of fish in the figure for which one fish of the pair seems to be

4. A dilation of the other?



5. A reflection of the other?

Complete the figures by including the reflection image of the object through the mirror line.



10.



3.



8. **N**

11.

14.

9. **A**

12. **E 3**

15.

16. Which figures look the same as their mirror images?

#9,11,14

17. What is it about these figures that causes them and their mirror images to look the same?

8.2 - Reflections

Def: The <u>reflection</u> of point P through line l is P itself if P lines on l. Otherwise, it is the point P' such that l is the perpendicular bisector of PP'.

Construction 8: To reflect a point through a line.

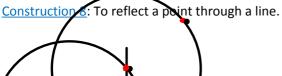
Def: A <u>translation</u> is the composite of two successive reflections through parallel lines.

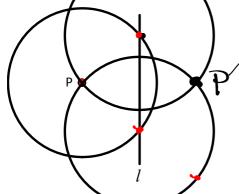
The distance between a point of the original figure and its translation image is called the *magnitude* of the translation.

Def: A <u>rotation</u> is the composite of two successive reflections through intersecting lines. The point in which the lines intersect is the *center* of rotation, and the measure of the angle through which a point of the original figure turns to coincide with its rotation image is called the *magnitude* of the rotation.

8.2 - Reflections

Def: The <u>reflection</u> of point P through line l is P itself if P lines on l. Otherwise, it is the point P' such that l is the perpendicular bisector of PP'.

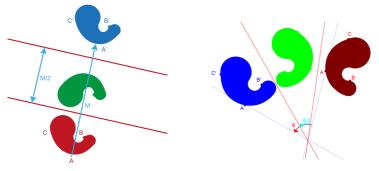




Def: A <u>translation</u> is the composite of two successive reflections through parallel lines.

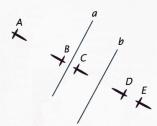
The distance between a point of the original figure and its translation image is called the *magnitude* of the

translation.



Def: A <u>rotation</u> is the composite of two successive reflections through intersecting lines. The point in which the lines intersect is the *center* of rotation, and the measure of the angle through which a point of the original figure turns to coincide with its rotation image is called the *magnitude* of the rotation.

In the figure below, $a\parallel b$ and birds A, B, D, and E are reflection images of bird C through either or both of the lines.



Which bird is the reflection image of

31. bird C through a?

32. bird B through b?

33. bird C through b?

34. bird D through a?

Which bird is the image of bird C as a result of successive reflections through

35. a and b?

36. b and a?

37. What transformation do exercises 35 and 36 illustrate?

31. 🗲

32. 巨

33.

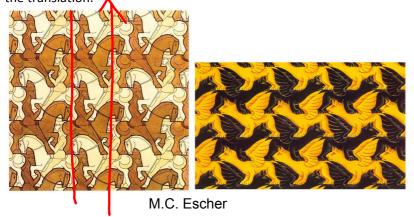
34. A

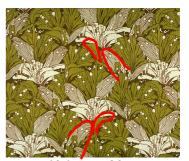
 $35. E \ge translations$

8.3 - Isometries and Congruence

Def: Two figures are <u>congruent</u> if there is an isometry such that one figure is the image of the other.

Def: A <u>glide reflection</u> is the composite of a translation and a reflection in a line parallel to the direction of the translation.





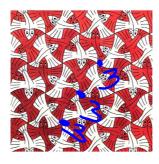
Koloman Moser

8.4 - Transformations and Symmetry

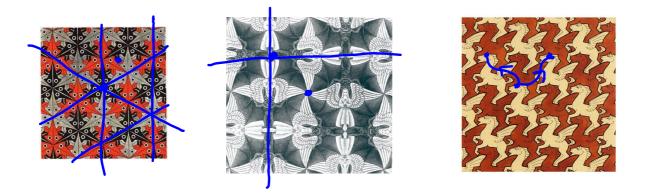
Def: A figure has <u>rotation symmetry</u> with respect to a point iff it coincides with its rotation image through less that 360° about the point.

A figure is said to have <u>n-fold rotation symmetry</u> iff the smallest angle through which it can be turned to look exactly the same is 360°/n.





Def: A figure has <u>reflection (line) symmetry</u> with respect to a line iff it coincides with its reflection image through the line. The line is sometimes called the <u>axis of symmetry</u>.



Def: A pattern has <u>translation symmetry</u> iff it coincides with a translation image.